# SONATA Series Hardware Reference Manual



**Stand-alone Motor Control System** 



This motion control system is stand-alone, easy-to-use, plug-and-play and cost effective solution for motion control applications.

Each system includes the power supplies, the motion controller, and the micro-stepper and/or servo motor drivers. The operator interface terminal makes the system totally stand-alone and allows the operator to interact with the motion controller without needing an additional PC.

This series supports up to 3 axes of motion.

The system can also be operated using an analog joystick or a trackball. The speed of the motor is proportional to the tilt angle of the joystick or the rotational speed of the trackball.

#### **INSTALLATION**

- 1) Turn-off the motion controller.
- 2) The HOME switch(s), if any, should be connected to at the negative side of the end of travel.
- 3) The normally closed or normally low limit switches must be connected to LIMITS connectors.
- 4) Connect the motor(s).
- 5) Connect the OUTPUT port of the motion controller to the INPUT port of the terminal using the supplied cable.
- 6) Connect the INPUT port of the motion controller to the OUTPUT port of the terminal using the supplied cable.
- 7) Connect the LCD port of the motion controller to the LCD port of the terminal using the supplied cable.
- 8) Turn on the system. After initialization, press or keys the X motor should jog in negative or positive directions.
- 9) Always turn off the system before connecting or disconnecting any component.

# **PIN ASSIGNMENT AND DESCRIPTION**

## X-MOTOR

8-pin Circular Connector

The X-axis motor should be connected to this connector.

PIN	NAME	STEPPING MOTOR	DC MOTOR	BRUSHLESS DC MOTOR
1	PHAX+	Phase A+	Arm+	Phase A
2	PHBX+	Phase B+	Not Connected	Phase B
3	РНВХ-	Phase B-	Not Connected	Not Connected
4	PHAX-	Phase A-	Arm-	Phase C
5	CHSIS	Connected to the Chassis Chassis		Connected to the Chassis
6		Not Connected	Not Connected	Not Connected
7		Not Connected	Not Connected	Not Connected
8		Not Connected	Not Connected	Not Connected

# Y-MOTOR

8-pin Circular Connector

The Y-axis motor should be connected to this connector.

PIN	NAME	STEPPING MOTOR	DC MOTOR	BRUSHLESS DC MOTOR
1	PHAY+	Phase A+	Arm+	Phase A
2	PHBY+	Phase B+	Not Connected	Phase B
3	РНВҮ-	Phase B-	Not Connected	Not Connected
4	PHAY-	Phase A-	Arm-	Phase C
5	CHSIS Connected to the Connected to the Chassis		Connected to the Chassis	Connected to the Chassis
6		Not Connected Not Cor		Not Connected
7	Not Connected Not		Not Connected	Not Connected
8	Not Connected		Not Connected	Not Connected

# **Z-MOTOR**

8-pin Circular Connector

The Z-axis motor should be connected to this connector.

PIN	NAME	STEPPING MOTOR	DC MOTOR	BRUSHLESS DC MOTOR
1	PHAZ+	Phase A+	Arm+	Phase A
2	PHBZ+ Phase B+ Not Connected		Not Connected	Phase B
3	PHBZ-	Phase B-	Not Connected	Not Connected
4	PHAZ-	Phase A-	Arm-	Phase C
5	CHSIS	Connected to the Chassis Connected to the Chassis		Connected to the Chassis
6		Not Connected	Not Connected Not Connected Not Con	
7		Not Connected	Not Connected	Not Connected
8		Not Connected	Not Connected	Not Connected

## **JOYSTICK**

25-pin DB-25, Female Connector

This port is used to connect an analog joystick. If a joystick is not used, three analog signals may be connected to this port.

Related commands are RSTSX, RSTSY and RSTSZ. Please refer to Operating and Programming Reference Manual

PIN	NAME	DESCRIPTION
1	ANALOG-X	Analog-X Input
2	ANALOG-Y	Analog-Y Input
3	HIGH-SPEED	High Speed Selection Input
4	MEDIUM-SPEED	Medium Speed Selection Input
5	LOW-SPEED	Low Speed Selection Input
6	W-SELECT	W-axis Selection Key
15	ANALOG-Z	Analog-Z Input
16	GND	System Ground
17	GND	System Ground
18	GND	System Ground
19	+5 VDC	+5 VDC
20	+5 VDC	+5 VDC
21	+5 VDC	+5 VDC

#### **X-LIMITS**

9-pin DB-9, Male Connector

The X-axis positive, negative and home switches should be connected to this port.

PIN	NAME	DESCRIPTION
1	POS-LIMIT-X *	X-Axis Positive Limit Switch Input
2	GND	System Ground
3	+5 VDC	+5 VDC
4	NEG-LIMIT-X *	X-Axis Negative Limit Switch Input
5	GND	System Ground
6	+5 VDC	+5 VDC
7	HOME-X **	X-Axis Home Switch Input
8	GND	System Ground
9	+5 VDC	+5 VDC

#### Y-LIMITS

9-pin DB-9, Male Connector

The Y-axis positive, negative and home switches should be connected to this port.

PIN	NAME	DESCRIPTION
1	POS-LIMIT-Y *	Y-Axis Positive Limit Switch Input
2	GND	System Ground
3	+5 VDC	+5 VDC
4	NEG-LIMIT-Y *	Y-Axis Negative Limit Switch Input
5	GND	System Ground
6	+5 VDC	+5 VDC
7	HOME-Y **	Y-Axis Home Switch Input
8	GND	System Ground
9	+5 VDC	+5 VDC

<sup>\*</sup> A normally closed or normally low switch should be placed between this pin and GND.

A 10 KOHM pull-up resistor is placed between all inputs and +5 VDC.

<sup>\*\*</sup> A normally closed or normally low switch should be placed between this pin and GND, if homing operation is required.

# **Z-LIMITS**

9-pin DB-9, Male Connector

The Z-axis positive, negative and home switches should be connected to this port.

PIN	NAME	DESCRIPTION
1	POS-LIMIT-Z *	Z-Axis Positive Limit Switch Input
2	GND	System Ground
3	+5 VDC	+5 VDC
4	NEG-LIMIT-Z *	Z-Axis Negative Limit Switch Input
5	GND	System Ground
6	+5 VDC	+5 VDC
7	HOME-Z **	Z-Axis Home Switch Input
8	GND	System Ground
9	+5 VDC	+5 VDC

## **X-ENCODER**

9-pin DB-9, Male Connector

The X-axis motor encoder and Hall Effect sensors, if available, should be connected to this port.

PIN	NAME	DESCRIPTION
1	+5 VDC	+5 VDC
2	CHSIS	Connected to the Chassis
3	ХСНВ	X-Motor Channel-B Quadrature Input
4	ХСНА	X-Motor Channel-A Quadrature Input
5	GND	System Ground
6	XHALL-B	X-Motor HALL-B Sensor Input
7	XHALL-C	X-Motor HALL-C Sensor Input
8	XHALL-A	X-Motor HALL-A Sensor Input
9		Not Connected

# Y-ENCODER

9-pin DB-9, Male Connector

The Y-axis motor encoder and Hall Effect sensors, if available, should be connected to this port.

PIN	NAME	DESCRIPTION
1	+5 VDC	+5 VDC
2	CHSIS	Connected to the Chassis
3	<b>У</b> СНВ	Y-Motor Channel-B Quadrature Input
4	YCHA	Y-Motor Channel-A Quadrature Input
5	GND	System Ground
6	YHALL-B	Y-Motor HALL-B Sensor Input
7	YHALL-C	Y-Motor HALL-C Sensor Input
8	YHALL-A	Y-Motor HALL-A Sensor Input
9		Not Connected

# **Z-ENCODER**

9-pin DB-9, Male Connector

The Z-axis motor encoder and Hall Effect sensors, if available, should be connected to this port.

PIN	NAME	DESCRIPTION
1	+5 VDC	+5 VDC
2	CHSIS	Connected to the Chassis
3	<b>Z</b> CHB	Z-Motor Channel-B Quadrature Input
4	ZCHA	Z-Motor Channel-A Quadrature Input
5	GND	System Ground
6	ZHALL-B	Z-Motor HALL-B Sensor Input
7	ZHALL-C	Z-Motor HALL-C Sensor Input
8	ZHALL-A	Z-Motor HALL-A Sensor Input
9		Not Connected

## **RS-232**

9-pin DB-9, Female Connector

This port should be connected to the RS-232 port of the host computer or PLC using the supplied cable.

PIN	NAME	DESCRIPTION
1		Not Connected
2	DATA-XMT	Data Transmit to PC
3	DATA-RCV	Data Receive from PC
4		Not Connected
5	GND	System Ground
6		Not Connected
7	RESET	RESET to Controller, Should Be Set to Clear
8		Not Connected
9		Not Connected

## **DISPLAY**

9-pin DB-9, Female Connector

This port should be connected to the DISPLAY port of the terminal using the supplied cable.

PIN	NAME	DESCRIPTION
1	LCD CLOCK	LCD CLOCK
2	LCD DATA	LCD DATA
3	LCD CS	LCD CHIP SELECT
4	+5 VDC	+5 VDC
5	GND	System Ground
6		Not Connected
7		Not Connected
8		Not Connected
9	+5 VDC	+5 VDC

Specifications are subject to change without notice.